







## THE GRIPPER FOR COLLABORATIVE ROBOTS

- Plug + Play and easy to program
- Ideal for precision assembly tasks
- Ergonomic shape for hand-guiding
- Built for industrial applications and harsh environments
- Automatic part detection, position feedback, and part validation



Pick & Place



Assembly



Machine Tending



**Quality Testing** 

4.7 KG

IP67

5,000,000 CYCLES WARRANTY\*

\*Excludes fingertips





Extenders sold separately

## TAKE FULL CONTROL

50-MM STROKE GRIPPER IS SUITED TO COLLABORATIVE ROBOTS

ADAPT THE HAND-E TO YOUR PARTS WITH ACCESSORIES OR CUSTOM FINGERTIPS



Force Copilot sold separately

## UNLOCK FULL POTENTIAL WITH FORCE COPILOT

**PATH RECORDING NODE** 

**INSERTION NODE** 

**FIND SURFACE NODE** 

**FORCE CONTROL NODE** 

SPECIFICATIONS	HAN	HAND-E	
Stroke (adjustable)	50 mm	2 in	
Grip force (adjustable)	20 to 185 N	4.5 to 41 lbf	
Form-fit grip payload	5 kg	11 lbs	
Friction grip payload*	4,7 kg	8.8 lbs	
Gripper mass	1 kg	2 lbs	
Position resolution (fingertip)	0.2 mm		
Closing speed (adjustable)	20 to 150 mm/s	0.8 to 5.9 in/s	
Communication protocol	Modbus RT	Modbus RTU (RS-485)	
Ingress protection (IP) rating	IP6	IP67	

<sup>\*</sup> Calculated for the use of silicon covered fingertips to grip a steel object, at a low robot acceleration.

## **WHAT'S NEXT?**

Get access to the Adaptive Grippers specifications at

support.robotiq.com

Chat with the Robotiq sales team:
iss@robotiq.com
1-888-ROBOTIQ





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<sup>\*\*</sup> All specifications provided for reference only. See user manual at support.robotiq.com for official specifications.