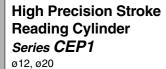


Stroke Reading Cylinder and Counter Series CE







P. 10-12-8



P. 10-12-18

Multi-counter Series CEU5 P. 10-12-27 **3-point Preset** Counter Series CEU1



P. 10-12-30

REC C□X

RE^A

C | Y

 MQ_{M}^{Q}

RHC

MK(2)

RS^Q RSA A

RZQ

МIS

CEP1

CE1

CE2

ML2B

C_G5-S

CV MVGQ

CC

RB

D-

-X

20-

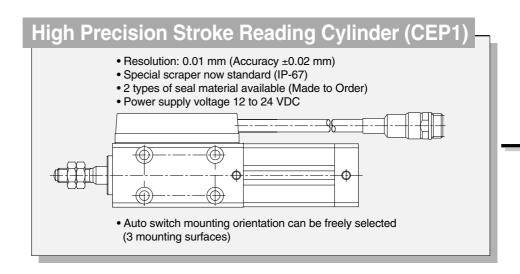
Achieve rationalization

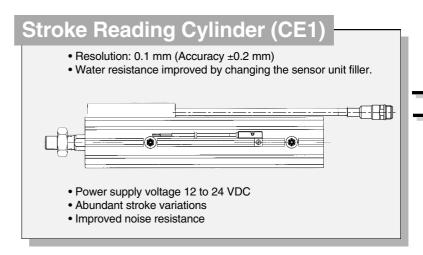
Stroke reading cylinder

Measurement is possible throughout the full stroke range.

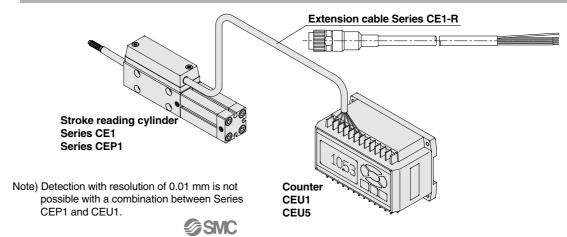
The home position can be anywhere — When the counter is reset by pressing within the cylinder stroke.

the cylinder rod to the reference plane, that point becomes the home position.





System Configuration



of production lines

with position feedback



Tolerances of preset values can be set. (CEU1, CEU5)

Tolerances can be set for preset values.

CEU1: ± set tolerance

CEU5: + set tolerance, – set tolerance (separate settings)

Simple operation

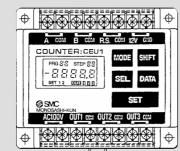
Multi-counter (CEU5)



Includes all functions of the CEU1.

- Output terminal: 5 points
- Number of output settings:
 20 points (Bank switching)
 31 points (Binary output)
- Communication function with RS-232C
- With BCD output (Option)
- Maximum counting speed 100 kHz
- Prescale function
- With multiplication switching (1, 2, 4 multiplication)
- DIN rail mountable
- 6 digits count display

3-point Preset Counter (CEU1)



- Output terminal: 3 points
- DIN rail mountable
- Hold output, Comparison output, One shot output

Series Variations

Series CE1

Bore size		Standard stroke (mm)									Manufacturable		
(mm)	25	50	75	100	125	150	175	200	250	300	400	500	stroke range
12	•	•	•	•	•	•							25 to 150
20	•	•	•	•	•	•	•	•	•	•			25 to 300
32		•	•	•	•	•	•	•	•	•	•	•	25 to 400
40				•	•	•	•	•		•		•	25 to 600
50								•		•		•	25 to 600
63								•					25 to 600

CEU1

Output transistor Power mode supply voltage	NPN	PNP
100 VAC	•	•
24 VDC	•	•

CEU5

Count data output	RS-232	C+BCD	RS-2	232C
Output transistor mode supply voltage	NPN	PNP	NPN	PNP
100 to 240 VAC	•	•	•	•
24 VDC	•	•	•	•

Series CEP1

Bore size	Standard stroke (mm)						
(mm)	25	50	75	100			
12 equivalent	•	•	•	•			
20 equivalent	•	•	•	•			

Extension Cable

	Cable length (m)				
	5	10	15	20	
_	•	•	•	•	



REA REC

C□X

CUY

MQM

RHC

MK(2)

RS♯

RZQ

MIS

CEP1

CE1

CE2

ML2B

CV

MVGQ

CC

RB

D-

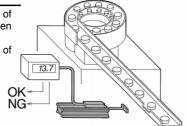
-X

20-Data

Application Example

Parts inspection

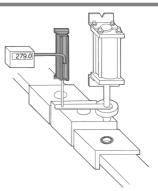
Measures the dimensions of parts, discriminates between good and defective articles, and prevents the mingling of different parts, etc.



Confirmation of press-in

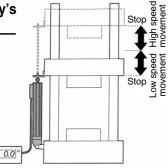
Can confirm the press-in of a hydraulic cylinder by detecting its stroke.

Even if the size of the workpiece changes, the point of press-in completion can be easily changed.



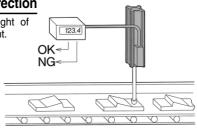
Detection of die assembly's deceleration point

Since the deceleration point of the die assembly can be set at will, it can be easily changed after replacement of the die assembly.



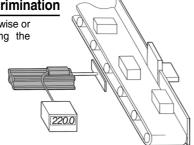
Discrimination of direction

Maintains a constant height of measuring workpiece height.



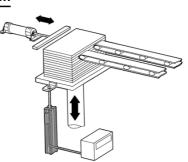
Length/breadth discrimination

Distinguishes either lengthwise or crosswise while correcting the position of a workpiece.



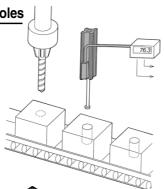
Detection of lifter position

Can continuously monitor a lifter's stroke.



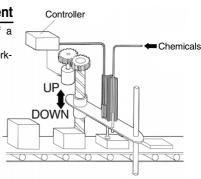
Inspection of machined holes

Can detect machined hole depth, burrs and foreign matter, etc.



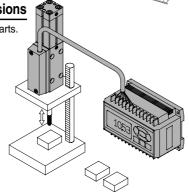
Nozzle height adjustment

Maintains a certain height of a workpiece and a nozzle by measuring the height of a workpiece.



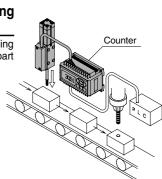
Measurement of dimensions

Can measure dimensions of parts.



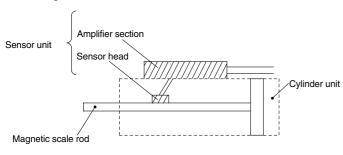
Measurement of machining dimensions

Performs adjustment of machining depth, etc. by measuring the part dimensions before machining.

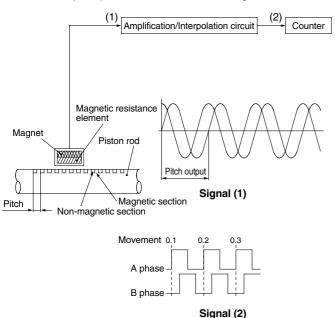


Measurement Principle

The amount of rod movement in the stroke reading cylinder is detected using an MR element (magnetic resistance element) whose resistance value changes due to magnetic force. The detection unit containing this MR element is called the sensor head. An amplifying circuit and a dividing circuit are required to produce output which can be read by the counter, and these are attached to the cylinder case. The sensor head and amplifier section together are referred to as the sensor unit.



The stroke reading cylinder is equipped with the capability of outputting the piston stroke movement as a pulse signal. The measurement principle is as shown in the drawing below.



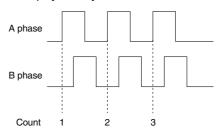
- Scales of magnetic layers and non-magnetic layers are etched at a certain pitch on the piston rod.
- 2. With movement of the piston rod, a sin, cos 2-phase signal (Signal (1)) is received by the magnetic resistance element. For this wave form, 1 pitch (0.8 mm) becomes exactly 1 cycle.
- This is amplified and divided into 1/8 parts. As a result, a 90° phase difference pulse signal of 0.1 mm/pulse (Signal (2)) is output.
- **4.** By measuring this pulse signal with the counter, it is possible to detect the piston position with a resolution of 0.1 mm.
- 5. In the case of the high precision stroke reading cylinder, the sin, cos 2-phase signal obtained in 2 is amplified and divided into 1/20 parts. As a result, a 90° phase difference pulse signal of 0.04 mm/pulse (Signal (2)) is output.
- 6. By multiplying this pulse signal by 4 with the counter, it is possible to detect the piston position with a resolution of 0.01 mm.

A/B Phase Difference Output (90° phase difference output)

When movement is expressed by a single line of pulses, it is impossible to accurately identify the current position, because pulse waves appear in both upward and downward directions.

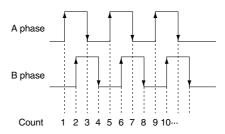
Accordingly, in A/B phase difference output, two lines of pulses are provided, wherein one line detects the movement and the other distinguishes the direction.

The CE1 also employs this system.



4 Times Multiplication Function

This function increases resolution 4 times by counting 4 for each cycle of pulses, instead of counting 1 for each cycle as is normally the case. In principle, this function counts each time there is a rise or fall in either of the A or B phase pulses.



Counting Speed (kHz, kcps)

Counting speed indicates the number of pulses that can be counted per second. If the stroke reading cylinder is operated at high speeds, pulse waves are output in shorter cycles. The counting speed of the counter must be higher than the pulse speed for the maximum piston speed when operating. Since the stroke reading cylinder outputs one pulse for each 0.1 mm of movement, 5,000 pulses will be output for each 500 mm of movement. Therefore, a speed of 500 mm/s is equivalent to 5 kcps (kHz), but a counting speed 2 to 3 times greater is recommended for actual operation.

Repeatability

The accuracy is the difference between the dimensions based upon the signals of the stroke reading cylinder and the absolute dimensions.

The maximum display error that will appear on the counter's digital display is equal to twice (±1 count) the resolution when the home position is reset and when dimensions are measured.

RE A

REC

C□X C□Y

MQ Q

RHC

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MK(2)

RS^Q_G

RS^H_A

MI®

CEP1

CE2

ML2B

C_GJ5-S

CV

MVGQ

CC RB

.1

J

D--X

20-





Specific Product Precautions

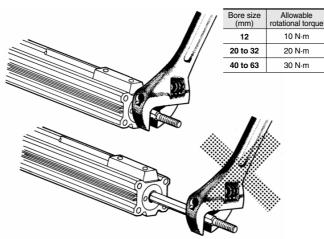
Be sure to read before handling.

Mounting

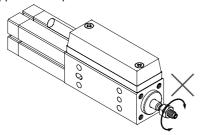
⚠ Caution

1. When screwing a nut or fitting, etc. onto the threaded section at the end of the piston rod, return the piston rod to its fully retracted position, and grasp the exposed portion of the rod across two parallel sides with a wrench. In the case of the high precision stroke reading cylinder, there are no parallel sides. Secure the workpiece with a double nut.

Note) Do not apply rotational torque to the piston rod.



- Operate the cylinder in such a way that the load is always applied in the axial direction.
 - In case the load is applied in a direction other than the axial direction of the cylinder, provide a guide to constrain the load itself.
 - When mounting a cylinder, centering should be done carefully.
- 3. Avoid using the air cylinder in such a way that rotational torque would be applied to the piston rod.



Be careful to avoid scratches or dents, etc. on the sliding sections of the piston rod.

Sensor Unit

- The sensor unit is adjusted to an appropriate position at the time of shipment. Therefore, never detach the sensor unit from the body.
- 2. The cylinder should be protected from contact with liquids such as coolants or coolant water. (CE1)
- 3. The sensor cable should not be pulled with a strong force.
- 4. Since the sensor for stroke reading cylinder adopts the magnetic method, it may result in malfunction if there is a strong magnetic field around the sensor. Use it under the external magnetic field with 14.5 mT or less.

This is equivalent to a magnetic field of approximately 18 cm in radius from a welding area using a welding amperage of almost 15,000 amperes. To use the system in a magnetic field that exceeds this value, use a magnetic material to shield the sensor unit.

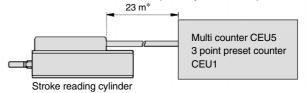
Switches or relays, etc. should not be installed in the power supply line (12 to 24 VDC).

Effects of Noise

⚠ Caution

When the stroke reading cylinder is used near a motor, welding machine or other source of noise generation, there is a possibility of miscounting. In this case, noise should be suppressed as much as possible and the following countermeasure should be taken.

- 1. Connect the shield wire to FG (flame ground).
- The maximum transmission distance for the stroke reading cylinder is 23 m, but since the output signal is a pulse output, the sensor cable should be wired separately from other power lines.

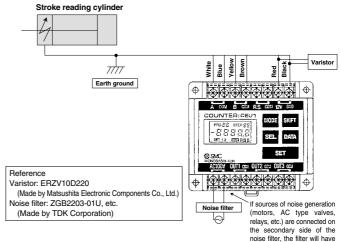


* When using SMC extension cable and counter.

Noise Counter Measures

Methods of dealing with noise are given below.

- 1. Connect only the shield wire to FG (frame ground).
- Use a power source separate from large motors and AC valves, etc.
- 3. Run the stroke reading cylinder's cable away from other power lines
- **4.** Install a noise filter in the 100 VAC power line, and install a varistor in the DC power supply of the sensor cable.



<Counting speed of counter>

When the speed of the stroke reading cylinder is greater than the counting speed of the counter, the counter will miscount.

For CE1 (when measuring to 0.1 mm), a counter should be used with a counting speed of 10 kHz (kcps) or more.

And for CEP1 (when measuring to 0.01 mm), use a counter with a counting speed of 50 kHz (kcps) or more when 4 times multiplication is input.

<Malfunction due to lurching and bounding>

When lurching or bounding occurs at the beginning or end of stroke reading cylinder, or due to other causes, the cylinder speed momentarily increases, and there is a possibility of exceeding the counting speed of the counter or the response speed of the sensor, thereby causing a miscount.

Handling of Technical Material

The instruction manuals should be read before using the Series CEP1 high precision stroke reading cylinder, CEU5 multi counter, CE1 scale cylinder and CEU1 3 point preset counter.

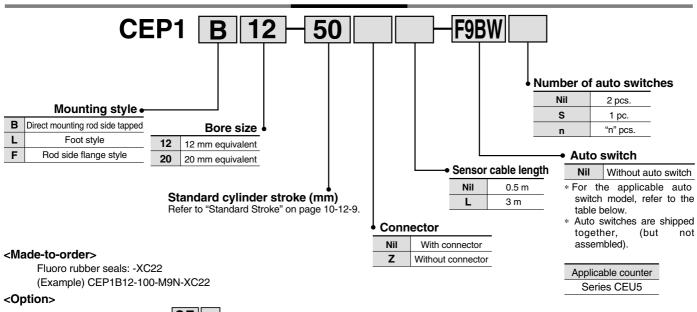
High Precision Stroke Reading Cylinder Non-rotating Piston Type

Series CEP1

ø12, ø20



How to Order



Extension cable CE1-R | 05 Cable length

05	5 m
10	10 m
15	15 m
20	20 m

• Juliix					
Nil	Extension cable				
С	Extension cable & connector				

Mounting Bracket Part No.

Cylinder part no.	Foot	Rod side flange
CEP1□12	CEP1-L12	CEP1-F12
CEP1□20	CEP1-L20	CEP1-F20

Applicable Auto Switch/Refer to page 10-20-1 for further information on auto switches.

Type	Cassial function	Electrical	rlight	Wiring	L	oad volta	ge	Auto swit	ch model		wire lenç	gth (m)	Pre-wire	A 1'	
Type	Special function	entry	Indicator light	(Output)	DC		AC	Perpendicular	In-line	0.5 (Nil)	3 (L)	5 (Z)	connector	Applica	ble load
Reed switch		Grommet		3-wire (NPN equivalent)	_	5 V		A96V	A96	•	•	ı	_	IC circuit	_
Ree	Reec		2-wire	24 V	12 V	100 V	A93V	A93	•	•	_	_	_	Relay, PLC	
				3-wire (NPN)	12 V	5 V, 12 V	5 V, 12 V	M9NV	M9N	•	•	0	0	IC circuit	
ح				3-wire (PNP)				M9PV	М9Р	•	•	0	0	io circuit	
witc				2-wire		12 V		M9BV	M9B	•	•	0	0		5.
Solid state switch		Grommet	met Yes	3-wire (NPN)			_	F9NWV	F9NW	•	•	0	0		Relay, PLC
Solid	Diagnostic indication (2-color indication)			3-wire (PNP)	5 V, 12 V			F9PWV	F9PW	•	•	0	0	IC circuit	
				2-wire		12 V		F9BWV	F9BW	•	•	0	0		
	Water resistant (2-color indication)			Z-WIIE		12 V		_	F9BA		•	0	0	_	

^{*} Lead wire length symbols:

0.5 m Nil 3 m L 5 m Z

(Example) M9N (Example) M9NL (Example) M9NZ

* Solid state switches marked with "O" are produced upon receipt of order.

[•] Refer to page 10-12-16 for details on other applicable auto switches than listed above.

For details about auto switches with pre-wire connector, refer to page 10-20-66.

High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1

Cylinder Specifications



Action	Double acting, Single re	od (Non-rotating piston)			
Fluid	Air				
Proof pressure	1.5 [1.5 MPa			
Maximum operating pressure	1.01	МРа			
Minimum operating pressure	ø12	ø20			
will ill fluin operating pressure	0.15 MPa	0.1 MPa			
Piston speed	50 to 30	00 mm/s			
Ambient and fluid temperature	0 to 60°C (No freezing)				
Lubrication	Non-lube				
Stroke length tolerance range	0 to 1.0 mm				
Cushion	With	nout			
Rod non-rotating accuracy	ø12	ø20			
	±2°	±3°			
Mounting	Direct mounting rod side tapped (Standard	dard), Foot style, Rod side flange style			
Thread tolerance	JIS Class 2				

JIS Symbol



Made to	Made to Order Specifications (For details, refer to page 10-21-1.)
Olas	(For details, refer to page 10-21-1.)

	(i or dotallo, refer to page 10 = 1 11)
Symbol	Specifications
-XC22	Fluoro rubber seals

Sensor Specifications

Cable	ø7, 6 core twisted pair shielded wire (Oil, Heat & Flame resistant)
Maximum transmission distance	23 m (when using SMC cable and counter)
Position detection method	Magnetic scale rod, sensor head < Incremental type>
Magnetic field resistance	14.5 mT
Power supply	10.8 to 26.4 VDC (Power supply ripple: 1% or less)
Current consumption	50 mA
Resolution	0.01 mm (With 4 times multiplication)
Accuracy	±0.02 mm ⁽¹⁾ (at 20°C)
Output type	Open collector (24 VDC, 40 mA)
Output signal	A/B phase difference output
Insulation resistance	500 VDC, 50 M Ω or more (between case and 12E)
Vibration resistance	33.3 Hz 6.8 G 2 hrs. each in X, Y directions 4 hrs. in Z direction
Vibration resistance	based upon JIS D 1601
Impact resistance	30 G 3 times each in X, Y, Z directions
Enclosure	IP-67 (IEC Standard) ⁽²⁾
Extension Cable (Option)	CE1-R* 5 m, 10 m, 15 m, 20 m

Note 1) This includes the digital display error of the counter (CEU5).

Moreover, the overall accuracy after mounting on equipment will vary depending on mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole.

Note 2) Except for the connector, the cylinder section is the equivalent of an SMC water resistant cylinder.

Cylinder Stroke

		Manufacturable			
Model	25	50	75	100	stroke range
CEP1B12	•	•	•	•	0 to 150
CEP1B20	•	•	•	•	0 to 300

But, as for stroke over 100 mm, its accuracy will be ± 0.05 mm. (at 20°C)

REA

REC

 $C \square X$

C □ Y

MQ M

RHC

MK(2)

RS G

RSA A

RZQ

MIS

CEP1 CE₁

CE2

ML2B

C_G5-S

CV

MVGQ

CC

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-X

20-



Weight (Without mounting bracket/connector)

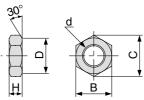
				(kg)				
Bore size	Cylinder stroke (mm)							
(mm)	25	50	75	100				
12	0.29	0.33	0.37	0.41				
20	0.62	0.68	0.74	0.80				

Proper Auto Switch Mounting Position

Regarding dimensions for the proper auto switch mounting position (at stroke end), refer to page 10-12-16

Rod End Nut Dimensions

(2 pcs. are attached as standard.)



Applicable bore size (mm)	d	Н	В	С	D
12	M5 x 0.8	3	8	9.2	7.8
20	M8 x 1.25	5	13	15.0	12.5

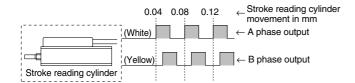
Material ø12, 20: Steel

Electrical Wiring

Output type

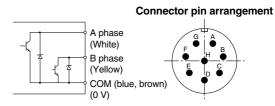
The output signal of the high precision stroke reading cylinder is A/B phase difference output (open collector output) as shown in the figure below.

The relation between the movement distance and the signal output of the high precision stroke reading cylinder is that for each 0.04 mm of movement a one pulse signal is output to both output terminals A and B. In order to measure with a discrimination of 0.01 mm, a counter with a 4 times multiplication function (CEU5) is required.



Input/Output

The input/output of the stroke reading cylinder is performed by a ø7 shielded twisted pair wire from the sensor section plus a connector.



Output circuit of stroke reading cylinder

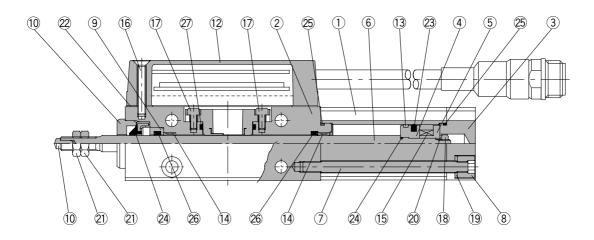
Signal

Oigilai		
Contact signal	Wire color	Signal name
Α	White	A phase
В	Yellow	B phase
С	Brown	COM (0 V)
D	Blue	COM (0 V)
E	Red	+12 to 24 V
F	Black	0 V
G	_	Shield

High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1

Construction

ø12, ø20



Component Parts

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Rod cover	Aluminum alloy	Hard chrome plated
3	Head cover	Aluminum alloy	Hard anodized
4	Piston A	Aluminum alloy	Hard anodized
(5)	Piston B	Aluminum alloy	Hard anodized
6	Piston rod	Carbon steel	Hard chrome plated
7	Tie-rod	Carbon steel	Chromated
8	Tie-rod nut	Carbon steel	Nickel plated
9	Seal ring	Aluminum alloy	White anodized
10	Centering location ring	Aluminum alloy	White anodized
11)	Rod end pin	Stainless steel	Quenched
12	Sensor unit	_	With or without connector
13	Wear ring	Special resin	
14)	Bushing	Cast iron	

No.	Description	Material	Note
15)	Magnet	Rare earth	
16	Cross recessed countersunk head screw	Chromium molybdenum steel	Nickel plated
17	Hexagon socket head cap screw	Stainless steel	
18	Hexagon nut	Carbon steel	Nickel plated
19	Spring washer	Steel wire	Nickel plated
20	Spring washer	Steel wire	Nickel plated
21)	Hexagon nut	Carbon steel	Rod end nut
22	Sensor case gasket	NBR	
23	Piston seal	NBR	
24)	Scraper	NBR	
25	Tube gasket	NBR	
26	Rod seal	NBR	
27)	O-ring	NBR	
28	O-ring	NBR	

^{*} Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.

RE A

REC

C□X

CUY

MQM

RHC

MK(2)

 RS_{G}^{Q}

RS^H

RZQ

МIs

CEP1

CE2

ML2B

C_G^J5-S

CV

MVGQ

CC

RB

J D-

-X

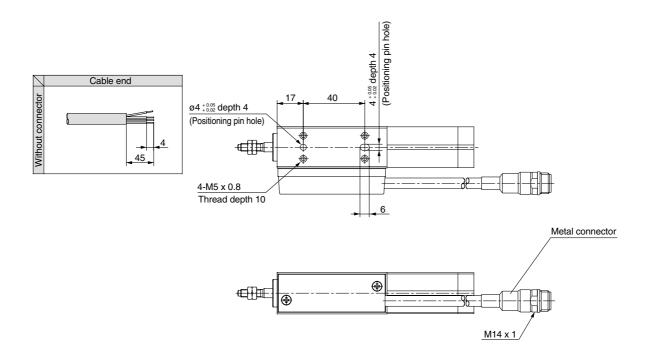
20-

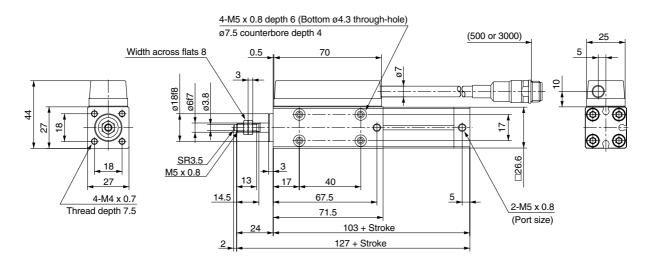


Dimensions: ø12

Direct mounting, rod side tapped style:

CEP1B12 — Stroke





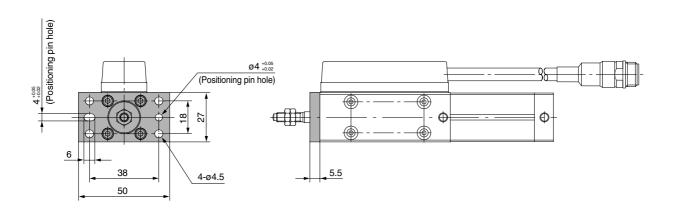
High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1

Φ

Foot style: CEP1L12 — Stroke 5.5 40 40.4.5 (a) out uid Burustisod (b) state (c) state

3.5

Rod side flange style: CEP1F12 — Stroke



40

51

RE A

REC

C□X

CUY

MQ M

RHC

MK(2)

RS G

RS^H

RZQ

MI s

CEP1

CE2

ML2B

C_G5-S

CV

MVGQ CC

RB

J

D-

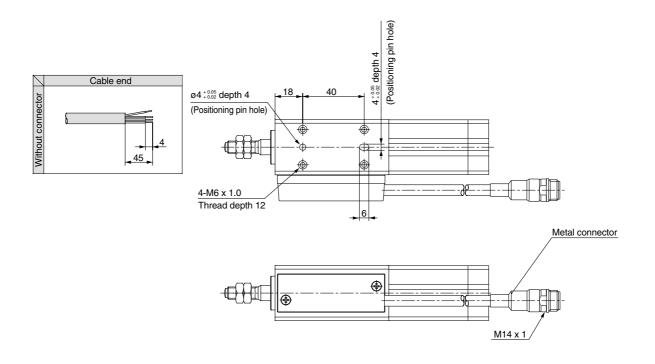
-X

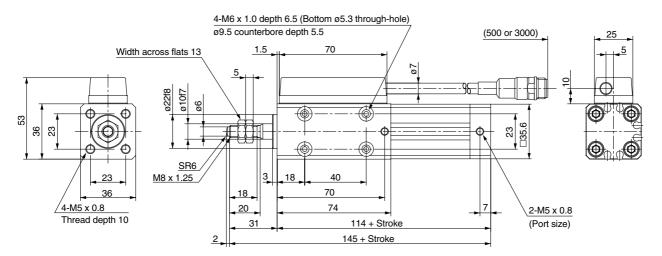
20-

Dimensions: ø20

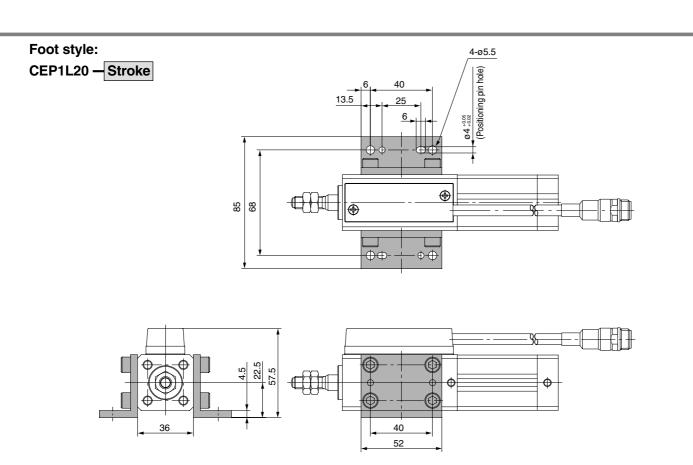
Direct mounting, rod side tapped style:

CEP1B20 - Stroke



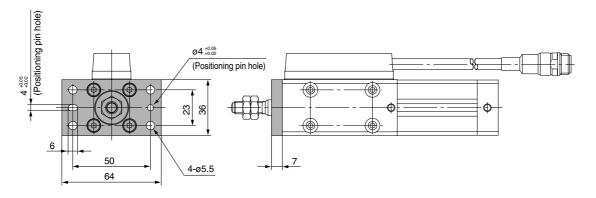


High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1



Rod side flange style:

CEP1F20 — Stroke



RE A

REC

C□X

CUY

MQ M

RHC

MK(2)

RS G

RS^H

RZQ

MI s

CEP1

CE1

CE2

ML2B

C_G5-S

CV

MVGQ

CC RB

J

D-

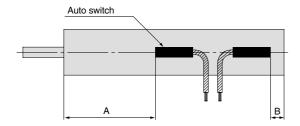
-X

20-



Series CEP1

Proper Auto Switch Mounting Position (Detection at stroke end) and Its Mounting Height



Proper Auto Switch Mounting Position

Auto switch model	D-A D-A	9□ 9□V	D-M9 D-M9 D-F9 D-F9	9□V	D-F9BAL		
(mm)	Α	В	Α	В	Α	В	
12	75	8	79	12	78	11	
20	82	12	86	16	85	15	

Operating Range

A	Bore size (mm)			
Auto switch model	12	20		
D-A9□/A9□V	6	10		
D-M9□/M9□V	2.5	3		
D-F9□W/F9□WV D-F9BAL	3	5		

^{*} Since this is a guideline including hysteresis, not meant to be guaranteed. (Assuming approximately ±30% dispersion)

There may be the case it will vary substantially depending on an ambient environment.

Other than the models listed in "How to Order", the following auto switches are applicable.

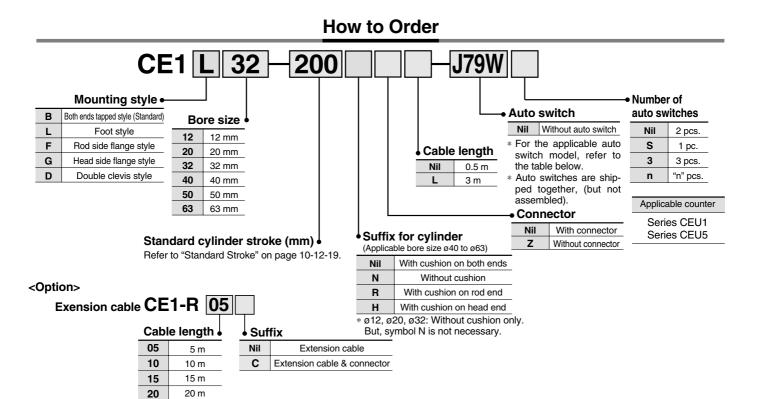
For detailed specifications, refer to page 10-20-1.

			· -			
	Type Model		Electrical entry	Features		
ı	D-A90		Grommet (In-line)	Without indicator light		
ı	Reed switch	D-A90V	Grommet (Perpendicular)	- Without indicator light		

* Normally closed (NC = b contact), solid state switch (D-F9G/F9H type) are also available. For details, refer to page 10-20-40.



Stroke Reading Cylinder Series CE1 ø12, ø20, ø32, ø40, ø50, ø63



Applicable Auto Switch/Refer to page 10-20-1 for further information on auto switches.

			light			Load voltage Rail mounting Direct mounting		ounting	Lead	wire l	ength	(m)*													
Туре	Special	Electrical	Indicator light	Wiring		C	AC	ø12 to	ø63	ø32 to	ø63	0.5	3	5	None	Pre-wire		icable ad							
	function	entry	Indic	(Output)	L L		AC	Perpendicular	In-line	Perpendicular	In-line	(Nil)	(L)	(Z)	(N)	connector	10	au							
				3-wire (NPN equivalent)	_	5 V	_	_	А76Н	A96V	A96	•	•	_	_	_	IC circuit	_							
Reed switch		Grommet			_	_	200 V	A72	A72H		_	•	•	_	_	_									
S P	_		Yes				100.1/	A73	A73H		_	•	•	•	_	_		 							
99				2-wire		12 V	100 V	_	_	A93V	A93	•	•	_	_	_	_	Relay, PLC							
ш		Connector			24 V	4 V		A73C	_	_	_	•	•	•	•	_		PLC							
	Diagnostic indication (2-color indication)	Grommet				_		A79W	_		_	•	•	_	_	_									
				3-wire (NPN)		5 V, 12 V	F7NV F7PV	F79	M9NV	M9N	•	•	0	_	0	IC airea it									
		Grommet		3-wire (PNP)				F7PV	F7P	M9PV	M9P	•	•	0	_	0	IC circuit								
등	_			0			10.1/	10.1/	10.1/	10.1/	12 V			F7BV	J79	M9BV	M9B	•	•	0	_	0			
switch		Connector		2-wire											J79C	_	_	_	•	•	•	•	_		
	Diagnostic indication		Yes	3-wire (NPN)	24 1/	F.V. 10.V		F7NWV	F79W	F9NWV	F9NW	•	•	0	_	0	IC airearia	Relay,							
sta	Diagnostic indication (2-color indication)		165	3-wire (PNP)	24 V	5 V, 12 V —	F V 5 V, 12 V	7 5 V, 12 V —	.4 V 5 V, 12 V	V, 12 V —	_	F7PW	F9PWV	F9PW	•	•	0	_	0	IC circuit	PLĆ				
Solid state	(2-color illulcation)	Grommet						F7BWV	J79W	F9BWV	F9BW	•	•	0	_	0									
S	Water resistant	Gioiilliet		2-wire		12 V		_	F7BA	_	F9BA	_	•	0	_	0	1 —								
	(2-color indication)							F7BAV	_		_	_	•	0	_	_]								
	Diagnostic indication (2-color indication)			4-wire(NPN)		5 V, 12 V		_	F79F		_	•	•	0	_	0	IC circuit								

* Solid state switches marked with "O" are produced upon receipt of order.

* Lead wire length symbols:

0.5 m Nil 3 m I

(Example) F73C

(Example) F73CL

(Example) F73CZ

5 m Z None ······ N (Example) A73CN

• Refer to page 10-12-26 for details on other applicable auto switches than listed above.

• For details about auto switches with pre-wire connector, refer to page 10-20-66.



Stroke Reading Cylinder Series CE1



Cylinder Specifications

Fluid		A	ir			
Proof pressure		1.5 [
Maximum operating pressure		1.0 l				
	ø12			ø20 to ø63		
Minimum operating pressure	0.07 MPa			0.05 MPa		
Piston speed		70 to 50	0 mm/s			
Ambient and fluid temperature	() to 60°C (N	lo freezing)		
Humidity	25 to	85% RH (N	lo condens	ation)		
Lubrication		Non-	lube			
Stroke length tolerance range	ø12, ø20: ⁺	1.0	ø32, ø	940, ø50, ø63: + 1.6		
With Air cushion	ø12, ø20, ø32····	None	ø40,	ø50, ø63····With		
Thread tolerance		JIS C	ass 2			
Rod non-rotating accuracy	ø12	ø20		ø12 ø20		ø32, ø40, ø50, ø63
riod non rotating doodiday	±2°	±1° ±0.8°				
Mounting	Both ends tapped (Standard), Foot style, Flange style, Double clevis style					
Auto switch	Reed type, Solid state type					

JIS Symbol



Sensor Specifications

Cable	ø7, 6 core twisted pair shielded wire (Oil, Heat & Flame resistant cable)
Maximum transmission distance	23 m (when using SMC cable and counter)
Position detection method	Magnetic scale rod Sensor head <non-rotating> <incremental type=""></incremental></non-rotating>
Magnetic field resistance	14.5 mT
Power supply	10.8 to 26.4 VDC (Power supply ripple: 1% or less)
Current consumption	40 mA
Resolution	0.1 mm/pulse
Accuracy	±0.2 mm (at 20°C) ⁽¹⁾
Output type	Open collector (24 VDC, 40 mA)
Output signal	A/B phase difference output
Insulation resistance	500 VDC, 50 M Ω or more (between case and 12E)
Vibration resistance	33.3 Hz, 6.8 G 2 hrs. each in X, Y directions 4 hrs. in Z direction based upon JIS D 1601
Impact resistance	30 G 3 times each in X, Y, Z directions
Enclosure	IP65 (IEC Standard) (2) Except connector tor part
Extension cable (Option)	5 m, 10 m, 15 m, 20 m

Note 1) This includes the digital display error of the counter (CEU1, CEU5).

Moreover, the overall accuracy after mounting on equipment will vary depending on the mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole.

Note 2) The cylinder section does not have a water resistant enclosure.

Mounting Bracket Part No.

Bore size (mm)	Foot *	Flange	Double clevis
12	CQ-L012	CQ-F012	CQ-D012
20	CQ-L020	CQ-F020	CQ-D020
32	CQ-L032	CQ-F032	CQ-D032
40	CQ-L040	CQ-F040	CQ-D040
50	CQ-L050	CQ-F050	CQ-D050
63	CQ-L063	CQ-F063	CQ-D063

Note 1) When ordering the foot bracket., order 2 pcs. per cylinder.

Note 2) Parts belonging to each bracket are as follows.

Foot, Flange/Body mounting bolts Double clevis/Clevis pin, type C snap ring for shaft, Body mounting bolts

Auto Switch Mounting Bracket Part No.

Bore size (mm)	Mounting bracket part no.	Note	Applicable auto switch
12 20	BQ-1	• Switch mounting screw (M3 x 0.5 x 8ℓ) • Square nut	D-A7□/A80 D-A7□H/A80H D-A73C/A80C
32 40 50 63	BQ-2	Switch mounting screw (M3 x 0.5 x 10ℓ) Switch spacer Switch mounting nut	D-A79W D-F7□/V D-F7□/J79 D-J79C D-F7□WV D-F7□W/J79W D-F7BAL/F7BAVL D-F79F/F7NTL

Standard Stroke

Bore size		Stroke (mm)														
(mm)	25	50	75	100	125	150	175	200	250	300	400	500	stroke range			
12	•	•	•	•	•	•	_	-	_	_	_	_	25 to 150			
20	•	•	•	•	•	•	•	•	_	_	_	_	25 to 300			
32	_	•	•	•	•	•	•	•	•	•	_	_	25 to 400			
40	_	_	_	•	•	•	•	•	•	•	•	•	25 to 600			
50	_	_	_	_	_	_	_	•	_	•	_	•	25 to 600			
63	_	_	_	_	_	_	_	•	_	•	_	•	25 to 600			

When the bore size is 12 mm and the stroke length is 100 mm or more, particular care should be taken regarding an offset load on the rod.

REC

REA

C□X

C□Y

MQ M

RHC

MIZ/O

MK(2)

RSG

RS^H

RZQ

MI w CEP1

CE1

CE2

ML2B

C_G5-S

CV

MVGQ

CC

RB

.

D-

-X

20-

Weight (Without mounting bracket/connector)

												(kg)
Bore size					Cyl	inder st	troke (n	nm)				
(mm)	25	50	75	100	125	150	175	200	250	300	400	500
12	0.29	0.33	0.36	0.4	0.43	0.47	_	_	_	_	_	_
20	0.51	0.58	0.65	0.72	0.79	0.86	0.93	1.0	_			_
32	-	0.94	1.05	1.15	1.26	1.36	1.47	1.58	1.79	2.0	_	_
40	_	_	_	1.7	1.83	1.95	2.08	2.2	2.45	2.7	3.2	3.7
50	-	_	_	_	_	_	_	3.4	_	4.1	_	5.5
63	_	_	_	_	_	_	_	4.2	_	5.0	_	6.6

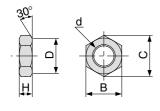
Proper Auto Switch Mounting Position

Regarding dimensions for the proper auto switch mounting position (at stroke end), refer to page 10-12-26

Rod End Nut Dimensions

(1 pc. is attached as standard.)

Material **ø12**, **20**: Steel **ø32** to **ø63**: Rolled steel



Part no.	Applicable bore size (mm)	d	н	В	С	D
NTJ-015A	12	M5 x 0.8	4	8	9.2	7.8
NT-02	20	M8 x 1.25	5	13	15.0	12.5
NT-04	32, 40	M14 x 1.5	8	22	25.4	21.0
NT-05	50, 63	M18 x 1.5	11	27	31.2	26

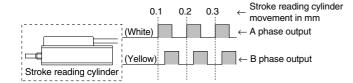
Electrical Wiring

Output type

The output signal of the stroke reading cylinder is A/B phase difference output (open collector output) as shown in the figure below.

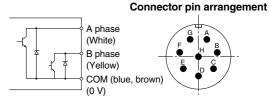
The relation between the movement distance and the signal output of the stroke reading cylinder is that for each 0.1 mm of movement a one pulse signal is output to both output terminals A and B.

Furthermore, the maximum response speed of the sensor for the stroke reading cylinder is at a maximum cylinder speed of 1500 mm/s (15 kcps).



Input/Output

The input/output of the stroke reading cylinder is performed by a $\varpi 7$ shielded twisted pair wire from the sensor section plus a connector.



Output circuit of stroke reading cylinder

Signal

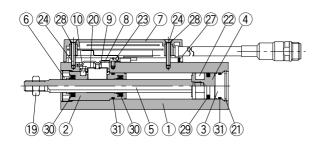
Contact signal	Wire color	Signal name
Α	White	A phase
В	Yellow	B phase
С	Brown	COM (0 V)
D	Blue	COM (0 V)
E	Red	+12 to 24 V
F	Black	0 V
G	_	Shield

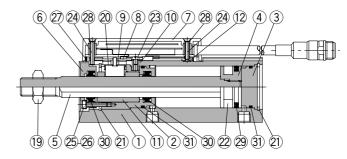
Stroke Reading Cylinder Series CE1

Construction

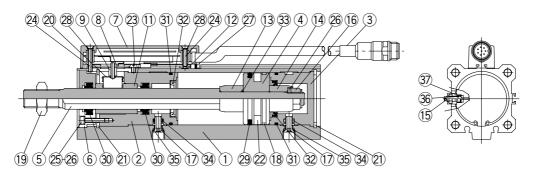
ø12, ø20

ø32





ø40 to ø63



Component Parts

No.	Description	Material	Note
1	Cylinder body	Aluminum alloy	
(2)	Rod cover	Brass	ø12 to ø20
	Hod cover	Aluminum alloy	ø32 to ø63
3	Head cover	Aluminum alloy	
(4)	Piston	Magnetic material	ø12
	FISIOII	Aluminum alloy	ø20 to ø63 (Built-in magnet)
<u>(5)</u>	Piston rod	Stainless steel	
6	Rod cover disk	Aluminum alloy	
7	Sensor unit	_	
8	Sensor setting bracket	Stainless steel	
9	Sensor setting piece assembly	1	ø20 to ø63
10	Pin	Stainless steel	ø12 to ø32
11)	Sensor guide	Lead-bronze casted	ø32 to ø63
12	Case setting nut	Carbon steel	ø32 to ø63
13	Cushion ring A	Rolled steel	ø40 to ø63
14)	Cushion ring B	Rolled steel	ø40 to ø63
15	Cushion valve	_	ø40 to ø63
16	Piston nut	Rolled steel	ø40 to ø63
17	Port joint	Stainless steel	ø40 to ø63

No.	Description	Material	Note
18)	Wear ring	Resin	ø40 to ø63
19	Rod end nut	Carbon steel	
20	Sensor setting plate	Cold rolled special steel strip	
21)	Type C snap ring	Carbon steel	
22	Magnet	_	
23	Round head Phillips screw	Carbon steel wire	
24)	Cross recessed countersunk head screw	Carbon steel wire	
25)	Hexagon socket head cap screw	Chromium molybdenum steel	
26	Spring washer	Steel wire	
27)	Case gasket	NBR	
28	Case screw gasket	NBR	
29	Piston seal	NBR	
30	Rod seal	NBR	
31)	Gasket	NBR	
32	Cushion seal	NBR	
33	Piston gasket	NBR	
34)	Port seal	NBR	
35)	Joint seal	NBR	
36	Valve seal	NBR	
(37)	Valve retainer seal	NBR	

^{*} Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.

RE A

REC

C□X

C□Y

MQ M

RHC

MK(2)

RSG

RS^H

RZQ

MI_s

CEP1

CE2

ML2B

C_G5-S

CV

MVGQ

CC

RB J

D-

-X

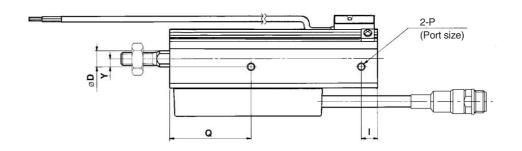
20-

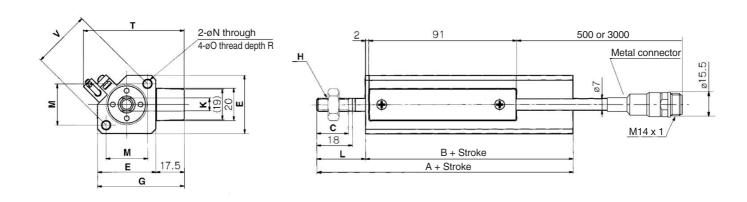
Series CE1

Dimensions: ø12, ø20

Both ends tapped style:

CE1B Bore size - Stroke





Bore size (mm)	Standard stroke	Α	В	С	D	E	G	Н	1	K	L	M
12	25, 50, 75, 100, 125, 150	94	69	15	6	25	42.5	M5 x 0.8	16	5.2	25	15.5
20	25, 50, 75, 100, 125, 150, 175, 200	106	78	15.5	10	36	53.5	M8 x 1.25	10	8	28	25.5

Bore size (mm)	N	0	P	Q	R	T *	V	Υ
12	_	M4 x 0.7	M5 x 0.8	47	7	53.5	22	7
20	5.5	M6 x 1	M5 x 0.8	50	15	62.5	36	5

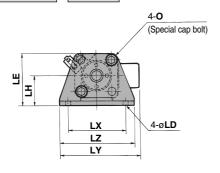
^{*} For rod nut and accessory bracket, refer to page 10-12-20. * Dimensions for auto switch model D-F79W.

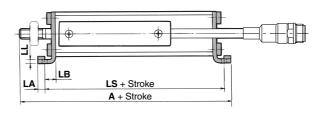


Stroke Reading Cylinder Series CE1

Foot style:

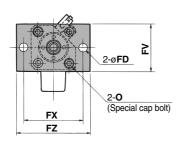
CE1L Bore size Stroke

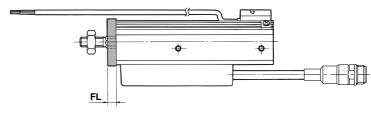




Rod side flange style:

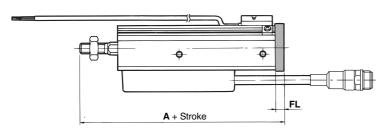
CE1F Bore size - Stroke

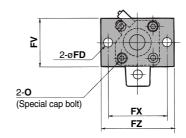




Head side flange style:

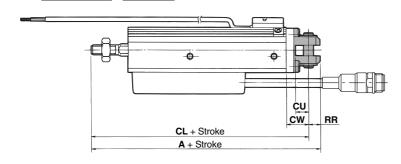
CE1G Bore size - Stroke

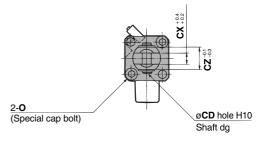




Double clevis style:

CE1D Bore size - Stroke





Bore size		Foot style										Rod side flange, Head side flange Head side flange							Double clevis style						
(mm)	Α	LA	LB	LD	LE	LH	LL	LS	LX	LY	LZ	FG	FL	FV	FX	FZ	Α	Α	CD	CL	CU	CW	СХ	CZ	RR
12	106.5	4.5	8	4.5	29.5	17	2	85	34	52	44	4.5	5.5	25	45	55	99.5	114	5	108	7	14	5	10	6
20	121	5.8	9.2	6.6	42	24	3.2	96.4	48	66.5	62	6.6	8	39	48	60	114	133	8	124	12	18	8	16	9
										•					•		•								

SMC

RE A

REC

C□X C□Y

MQ Q

RHC

MK(2)

RS^Q_G

RZQ

MI s

CEP1

CE2

ML2B

C_G5-S

CV

MVGQ

CC RB

J

D-

-X

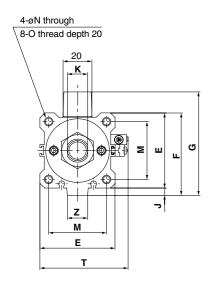
20-

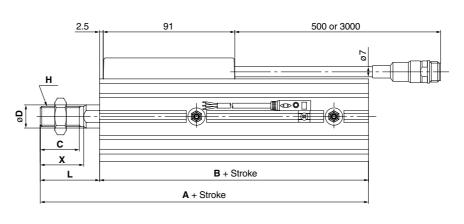
Series CE1

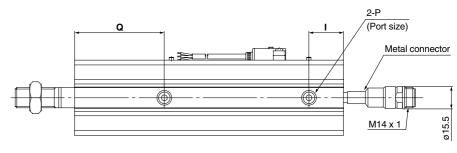
Dimensions: ø32, ø40, ø50, ø63

Both ends tapped style:

CE1B Bore size - Stroke







Bore size (mm)	Standard stroke	Α	В	С	D	E	F	G	Н	ı	J	K
32	50, 75, 100, 125, 150, 175, 200, 250, 300	131	90	27	16	45	49.5	64	M14 x 1.5	14	4.5	14
40	100, 125, 150, 175, 200, 250, 300, 400, 500	177	136	27	16	52	57	71.5	M14 x 1.5	24	5	14
50	200, 300, 500	193	144	32	20	64	71	85.5	M18 x 1.5	25.5	7	18
63	200, 300, 500	194	145	32	20	77	84	98.5	M18 x 1.5	21	7	18

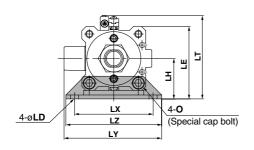
Bore size (mm)	L	M	N	0	Р	Q	T *	Х	Z
32	41	34	5.5	M6 x 1	Rc 1/8	56	57.5	30	14
40	41	40	5.5	M6 x 1	Rc 1/8	62	64.5	30	14
50	49	50	6.6	M8 x 1.25	Rc 1/4	61.5	76.5	35	19
63	49	60	9	M10 x 1.5	Rc 1/4	64	89.5	35	19

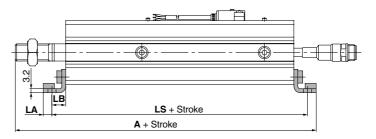
^{*} For rod nut and accessory bracket, refer to page 10-12-20. * Dimensions for auto switch model D-F79W.

Stroke Reading Cylinder Series CE1

Foot style:

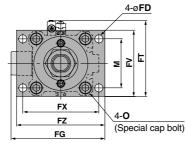
CE1L Bore size - Stroke

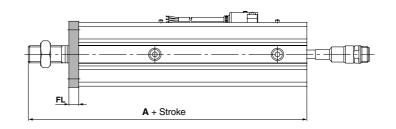




Rod side flange style:

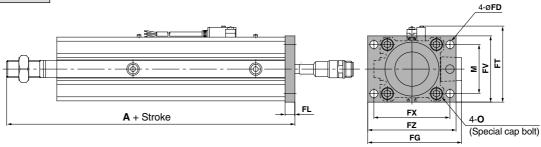
CE1F Bore size - Stroke





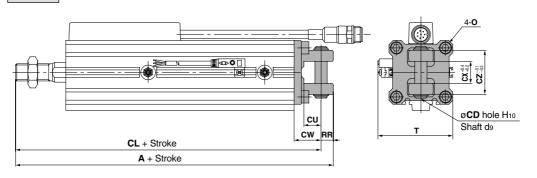
Head side flange style:

CE1G Bore size - Stroke



Double clevis style:

CE1D Bore size - Stroke



Bore size					Fo	ot sty	yle					Rod side flange, Head side flange			Head side flange	Double clevis style													
(mm)	Α	LA	LB	LD	LE	LH	LS	LT*	LX	LY	LZ	FD	FG	FL	FT*	F۷	FX	FZ	М	Α	Α	CD	CL	CU	CW	СХ	CZ	RR	Т
32	148	5.8	11.2	6.6	52.5	30	112.4	65	57	72.5	71	5.5	69.5	8	59	48	56	65	34	139	161	10	151	14	20	18	36	10	57.5
40	195.2	7	11.2	6.6	59	33	158.4	71.5	64	79.5	78	5.5	76.5	8	65.5	54	62	72	40	185	209	10	199	14	22	18	36	10	64.5
50	215.7	8	14.7	9	71	39	173.4	83.5	79	94	95	6.6	91	9	78	67	76	89	50	202	235	14	221	20	28	22	44	14	76.5
63	219.2	9	16.2	11	84.5	46	177.4	97	95	109.5	113	9	107	9	91	80	92	108	60	203	238	14	224	20	30	22	44	14	89.5
						. =																							

^{*} Dimensions for auto switch model D-F79W.

RE A

REC

C□X C□Y

MQ Q

RHC

nnc

MK(2)

RS^Q

RS^H

RZQ

MI s

CEP1

CE1

CE2

ML2B

C_G5-S

CV

MVGQ

CC

RB

J

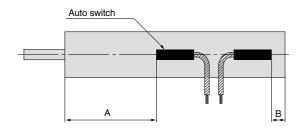
D--X

20-



Series CE1

Proper Auto Switch Mounting Position (Detection at stroke end)



Proper Auto Switch Mounting Position

Auto switch model	D-A D-A		D-A730 D-F7 / D-F7 \ D-F7 \ D-F7B	J79 V/J79C W/J79W WV	D-A	79W	D-F7	'NTL	D-A	9□ 9□V	D-M9 D-F9	D-M9□ D-M9□V D-F9□W D-F9□WV		D-F9BAL	
(mm)	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В	
12	40.5	4	41	4.5	38	2	46	9.5	39.5	3	43.5	7	42.5	6	
20	47	13	47.5	13.5	44.5	10.5	52.5	18.5	46	12	50	16	49	15	
32	55	17	5.5	17.5	52.5	14.5	60.5	22.5	54	16	58	20	57	19	
40	79	39	79.5	39.5	76.5	36.5	84.5	44.5	78	38	82	42	81	41	
50	82	44	82.5	44.5	79.5	41.5	87.5	49.5	81	43	85	47	84	46	
63	85.5	41.5	86	42	83	39	91	47	84.5	40.5	88.5	44.5	87.5	43.5	

Operating Range

A. the control of the			Bore siz	ze (mm)		
Auto switch model	12	20	32	40	50	63
D-A7□/A80 D-A7H/A80H D-A73C/A80C	10	12	12	11	10	12
D-A79W	13	13	13	14	14	16
D-A9□/A9□V	_	_	9.5	9.5	9.5	11.5
D-F7□/J79 D-F7□V/J79C D-F7□W/F7□WV D-J79W/F7NTL D-F7BAL/F7BAVL/F79F	5.5	5.5	6	6	6	6.5
D-M9□/M9□V	_	_	4.5	4.5	4.5	4.5
D-F9□W/F9□WV D-F9BAL	_	_	5.5	5.5	5.5	6

^{*} Since this is a guideline including hysteresis, not meant to be guaranteed. (Assuming approximately ±30% dispersion)
There may be the case it will vary substantially depending on an ambient environment.

Other than the applicable auto switches listed in "How to Order", the following auto switches can be mounted. For detailed specifications, refer to page 10-20-1.

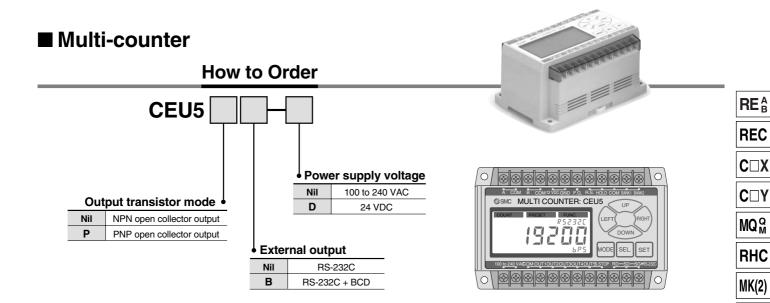
Туре		Model	Electrical entry (Fetching direction)	Features	Applicable bore size (mm)
		D-A80	Grommet (Perpendicular)		
		D-A80H	Grommet (In-line)	Without	12 to 63
Reed swit	ch	D-A80C	A80C Connector (Perpendicular)		
		D-A90	Grommet (In-line)	light	00 to 00
		D-A90V	Grommet (Perpendicular)		32 to 63
Solid state s	witch	D-F7NTL	Grommet (In-line)	With timer	12 to 63

^{*} With pre-wire connector is available for D-F7NTL type, too. For details, refer to page 10-20-66.

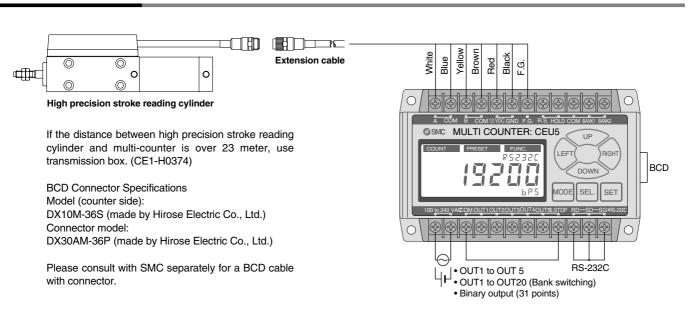
^{*}Normally closed (NC = b contact), solid state switch (D-F9G/F9H type) are also available. For details, refer to page 10-20-40.

Series CEU/Series CE

Counter/Extension Cable



Connection Method



RSG

RS^H

RZQ

MIS

CEP1

CE₁

CE2

ML2B

C_G^J5-S

CV

MVGQ

CC

RB

D-

-X

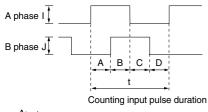
20-

Series CEU5

Multi-counter/Specifications

Model	CEU5	CEU5-D	CEU5P	CEU5P-D	CEU5B	CEU5B-D	CEU5PB	CEU5PB-D				
Туре				Multi-c	counter							
Mounting			Sur	face mounting (D	IN rail or Screw	stop)						
Operating system				Adding - sub	tracting type							
Operation mode			Operating m	ode, Data setting	mode, Function	setting mode						
Reset system		External reset terminal										
Display system		LCD (With back light)										
Number of digits		6 digits										
Memory holding (Storage medium)	Setting value (al	ng value (always held), Count value (Hold/Non-hold switching), {E²ROM (Warning display after writing approx. 800,000 times: E2FUL										
Input signal type		Count input, Control signal input (Reset, Hold, Bank selection)										
Count input		No-voltage pulse input										
Pulse signal system		90° phase difference input *1/ UP/DOWN separate input *2										
Counting speed		100 kHz *1										
Control signal input		Voltage input (12 VDC or 24 VDC)										
Sensor power supply		10.8 to 13.2 VDC, 60 mA										
Output signal type	F	Preset output, Cylinder stop output Preset output, Cylinder stop output, BCD output										
Preset output configuration		Compare/Hold/One-shot (100 ms fixed pulse)										
Output type			Sepa	arate 5 point outp	out/Binary code o	utput						
Output delay time				5 ms or less (fo	r normal output)							
Communication system				RS-2	232C							
Output transistor mode	NPN oper Max 30 VI			n collector DC, 50 mA	NPN oper Max 30 VD			en collector OC, 50 mA *3				
Power supply voltage	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC				
Power consumption	20 VA or less	10 W or less	20 VA or less	10 W or less	20 VA or less	10 W or less	20 VA or less	10 W or less				
Withstand voltage				en case and AC en case and sign								
Insulation resistance			Betwe	en case and AC	line: 500 VDC, 5	0 MΩ or more						
Ambient temperature				0 to 50°C (1	No freezing)							
Ambient humidity		35 to 85% RH (No condensation)										
Noise resistance	Square wa	Square wave noise from a noise simulator (pulse duration 1 μs) between power supply terminals ±2000 V, I/O line ±600 V										
Shock resistance		Endurance 10 to 55 Hz; Amplitude 0.75 mm; X, Y, Z for 2 hours each										
Impact resistance		Endurance 10 G; X, Y, Z directions, 3 times each										
Weight				350 g	or less							

*1) 90° phase difference input



2.5 µsec or more required

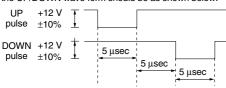
 $t:10\ \mu sec$ or more required

Counting speed
$$f = \frac{1}{t} = \frac{1}{10 \times 10^{-6}} = 100000 \text{ Hz}$$

 $\cong 100 \text{ kHz}$

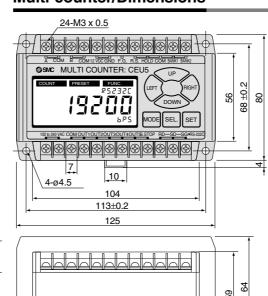
* 2) UP/DOWN input

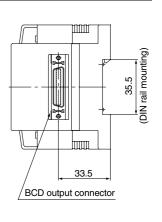
Input wave form conditions: At a maximum of 100 kHz, the UP/DOWN wave form should be as shown below.

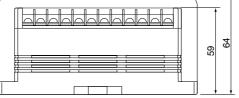


* 3) 15 mA when BCD is output.

Multi-counter/Dimensions









Wiring with External Equipment

<Wiring with multi counter CEU5>

1. Wiring of power source for driving counter
For power source for driving counter, use the one
with 90 to 264 VAC. 50/60 Hz or 21.6 to 264

with 90 to 264 VAC, 50/60 Hz or 21.6 to 264 VDC, 0.4 A or more.

2. Wiring for control signal input (Selection among Reset, Hold, Bank)

Make each control signal to be the transistor which can run more than 15 mA or the contact output. Input time for reset signal should be more than 10 ms. Bank selection and hold will function only when the input signal is applied.

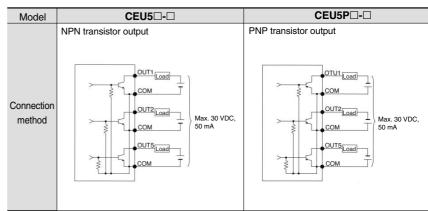
COM is common to each signal input. Applicable to NPN and PNP input. Use 24 VDC or 12 VDC for the power source of COM. Connect DC—when PNP is applied, and DC+ when NPN is applied.

3. Output circuit

There are two outputs, the NPN open collector and the PNP open collector.

The maximum rating is 30 VDC, 50 mA. Operating the controller by exceeding this voltage and amperage could damage the electric circuit.

Therefore, the equipment to be connected must be below this rating.



* However, the COM of the input circuit and the COM of the output circuit are electrically insulated from each other.

RE A

REC

C□X

MQ Q

RHC

niic

MK(2)

RS^Q_G

RS^H

RZQ

- -- \

MI S CEP1

CE1

CE2

ML2B

C_GJ5-S

CV

MVGQ

CC

RB

D-

-X

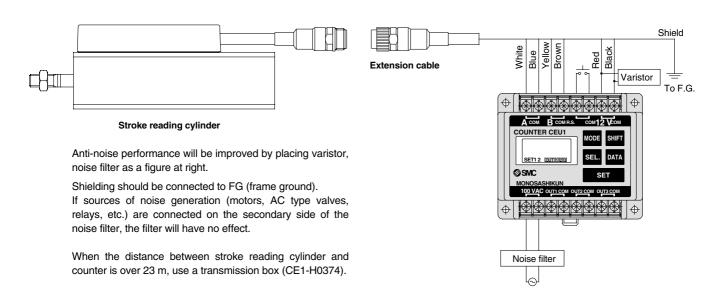
20-



Series CEU1

How to Order CEU1 Counter drive power supply Nil 100 VAC D 24 VDC Output mode selection Nil NPN open collector output P NPP open collector output P PNP open collector output

Connection Method

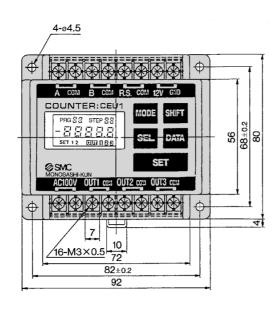


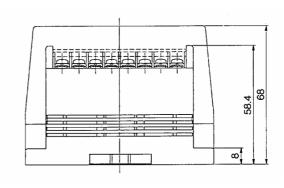


3-point Preset Counter/Specifications

Model	CEU1	CEU1P	CEU1-D	CEU1P-D					
Туре	0=01	3-point pre	set counter						
Mounting		· · ·	IN rail or Screw stop)						
Operating system		Adding - sub	tracting type						
Operation modes		Operating mode,	Data setting mode						
Reset system		External reset terminal							
Display system		LCD (With	back light)						
Number of digits		5 digits display (-	9999.9 to 9999.9)						
Memory holding {Storage medium}	Preset data (always he	eld) {E ² ROM (Warning o	lisplay after writing appr	rox. 65,000 times: /='_)}					
Input signal type		Count input,	Reset input						
Count input		No-voltage pulse input							
Pulse signal system		90° phase difference input							
Counting speed		20 kHz							
Reset input	R.S. and CO	R.S. and COM terminals are shorted for 10 ms or more (Pulse input)							
Sensor power supply		10.8 to 13.2 VDC, 60 mA							
Output signal type		Preset	output						
Preset output configuration	(Compare/Hold/One-sh	ot (100 ms fixed pulse)					
Output delay time		5 ms	or less						
Output transistor mode	NPN open collector Max. 30 VDC, 50 mA	PNP open collector Max. 30 VDC, 50 mA	NPN open collector Max. 30 VDC, 50 mA	PNP open collector Max. 30 VDC, 50 mA					
Power supply voltage	80 to 120 V	AC 50/60 Hz	21.6 to 2	26.4 VDC					
Power consumption	10 VA	or less	5 W c	or less					
Withstand voltage			line: 1500 VAC for 1 n nal ground: 500 VAC fo						
Insulation resistance	Betw	een case and AC line	: 500 VDC, 50 MΩ or ι	more					
Ambient temperature		0 to 50°C (wit	hout freezing)						
Ambient humidity		35 to 85% RH (No condensation)							
Noise resistance	Square wave noise from a no	ise simulator (pulse duration 1	μs) between power supply term	inals ±1500 V, I/O line ±600 V					
Shock resistance	Endurance 1	0 to 55 Hz; Amplitude	0.75 mm; X, Y, Z for 2	2 hours each					
Impact resistance	Er	ndurance 10 G; X, Y, Z	directions, 3 times ea	ch					
Weight		250 g	or less						

3-point Preset Counter/Dimensions





RE A

REC

C□X

C□Y

MQ M

RHC

MK(2)

RS^Q_G

RS^H_A

RZQ

MI w

CEP1

CE2

ML2B

C_G5-S

CV MVGQ

СС

RB

J

D-

-X

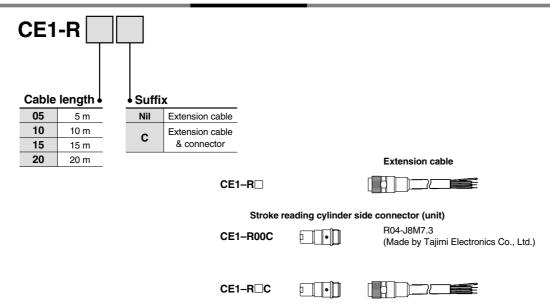
20-



Series CEU

■ Extension Cable

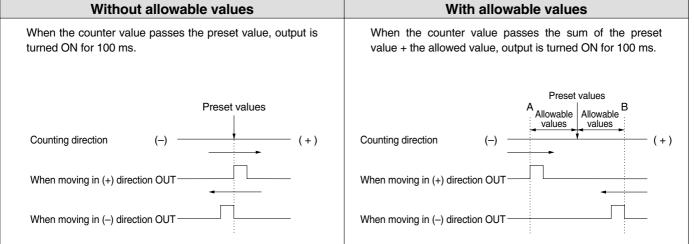
How to Order



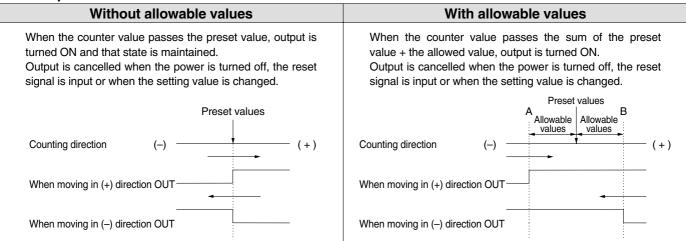


Operating Condition of each Output Mode

One-shot Output



Hold Output



Compare Output

Without allowable values	With allowable values								
Output is turned ON only when the counter value coincides with the preset value.	When the counter value passes the sum of the presvalue + the allowed value, output is turned ON.								
Preset values (+)	Preset values A Allowable values Counting direction (-)								
When moving in (+) direction OUT	When moving in (+) direction OUT								
When moving in (–) direction OUT	When moving in (–) direction OUT								

SMC

REA

REC

C□X

C□Y

MQ Q

RHC

11110

MK(2)

RS G

RS^H

RZQ

МIS

CEP1

CE1

CE2

ML2B

C_G^J5-S

CV

MVGQ

CC

RB

D-

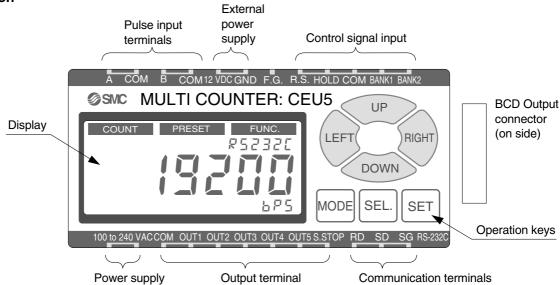
D-

20-

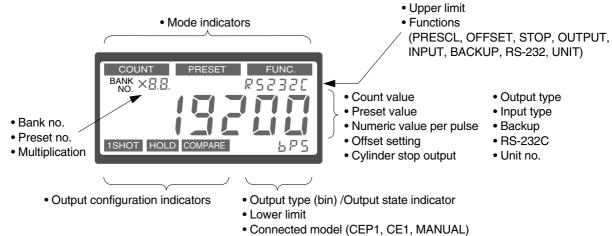
Series CEU

CEU5 Operation

Parts description



Display detail



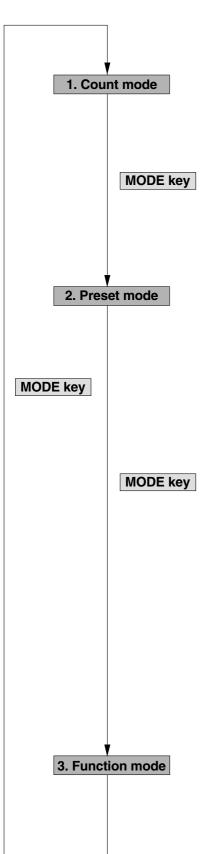
• RS-232C communication speed unit (bps)

Key and Functions

Key	Functions
MODE	Changes the mode. In any given condition, it shifts to the next mode. Does not write data.
SEL.	Shifts the cursor to the next item. Does not write data.
SET	Writes displayed data into the memory when setting.
RIGHT	Shifts the cursor to the right when setting numerical values.
LEFT	Shifts the cursor to the left when setting numerical values.
UP	Changes the contents of a setting. Increases the value when setting numerical values.
DOWN	Changes the contents of a setting. Decreases the value when setting numerical values.

In the explanations of the operating method, references to "Direction keys" indicate the 4 keys RIGHT, LEFT, UP and DOWN.

Mode cycle using mode key



Basic Operation

- SET key
 - : In any of the conditions (1) through (5), this writes the display data into the memory and shifts to (1).
- SEL. key : Shifts to the next item, but does not write data.
- MODE key : In any given condition, this shifts to the next mode, but does not write data.
- Direction keys: LEFT/RIGHT keys shift the digits, and UP/DOWN keys

increase or decrease numerical values.

1. Explanation of display in count mode

Normal output display Binary output display

Displays current output bank Displays only when matched with preset





Displays output state of each OUT terminal

SEL. key

Display of binary output selection.

2. Setting of preset mode



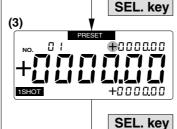
Selection of preset No.

- Select a preset number from 1 to 31 with the UP/DOWN keys.
- Shift to the next item with the SEL. key.

(2)+000000 +00000.00

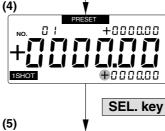
Setting the preset values

- Shift the digits with the LEFT/RIGHT keys, and increase or decrease the numerical values with the UP/DOWN keys.
- Shift to the next item with the SEL. key.



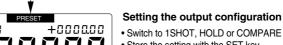
Setting the upper limit tolerance

- Set numerical values in the same way with the direction keys.
- ullet When \pm is selected, the lower limit display is cleared and \pm setting
- Shift to the next item with the SEL. key.



Setting the lower limit tolerance

- Set numerical values in the same way with the direction keys.
- \bullet When \pm is selected in the upper limit setting , this item is not displayed.
- Shift to the next item with the SEL. key.



- Switch to 1SHOT, HOLD or COMPARE with the UP/DOWN keys.
- Store the setting with the SET key.
- The SEL. key only shifts to another item without storing the setting.

RE A **REC**

C□X

C□Y

MQ M

RHC

MK(2)

RSa

RS^H

RZQ

MI®

CEP₁

CE₁ CE₂

ML2B

C25-S

CV

MVGQ

CC

RB

D-

-X

20-

Data



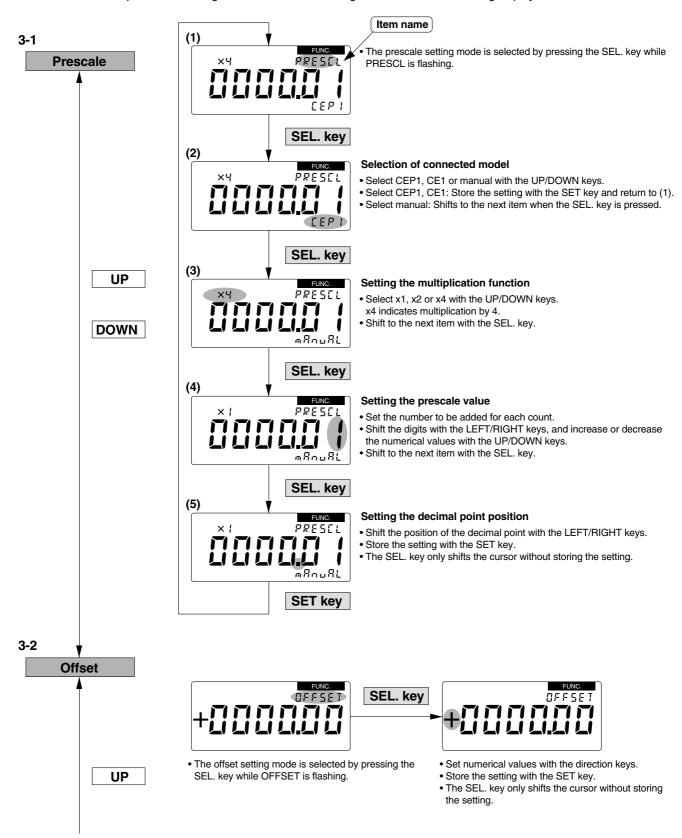
니 니.니 니 COMPARE + [] [] [] [] []

SET key

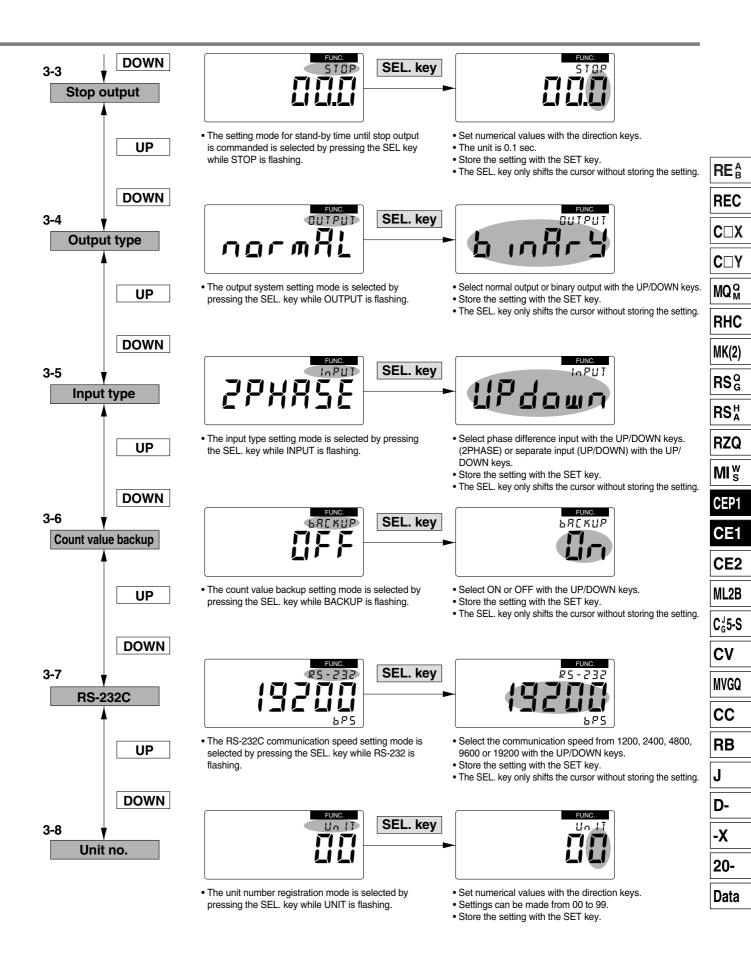
CEU5 Operation

3. Explanation of settings in the function mode

If the UP/DOWN keys are pressed when an item name is flashing, it shifts to another setting item. When the SEL key is pressed, the cursor shifts and it is possible to change the content of the setting for the item which is being displayed.

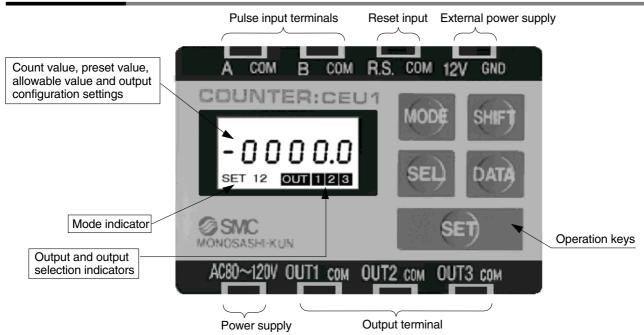


Counter CEU



Series CEU

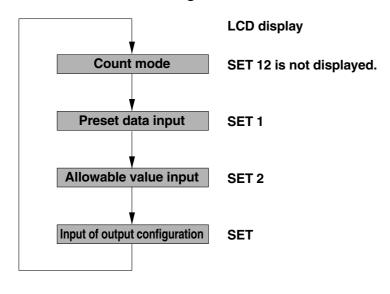
CEU1 Operation



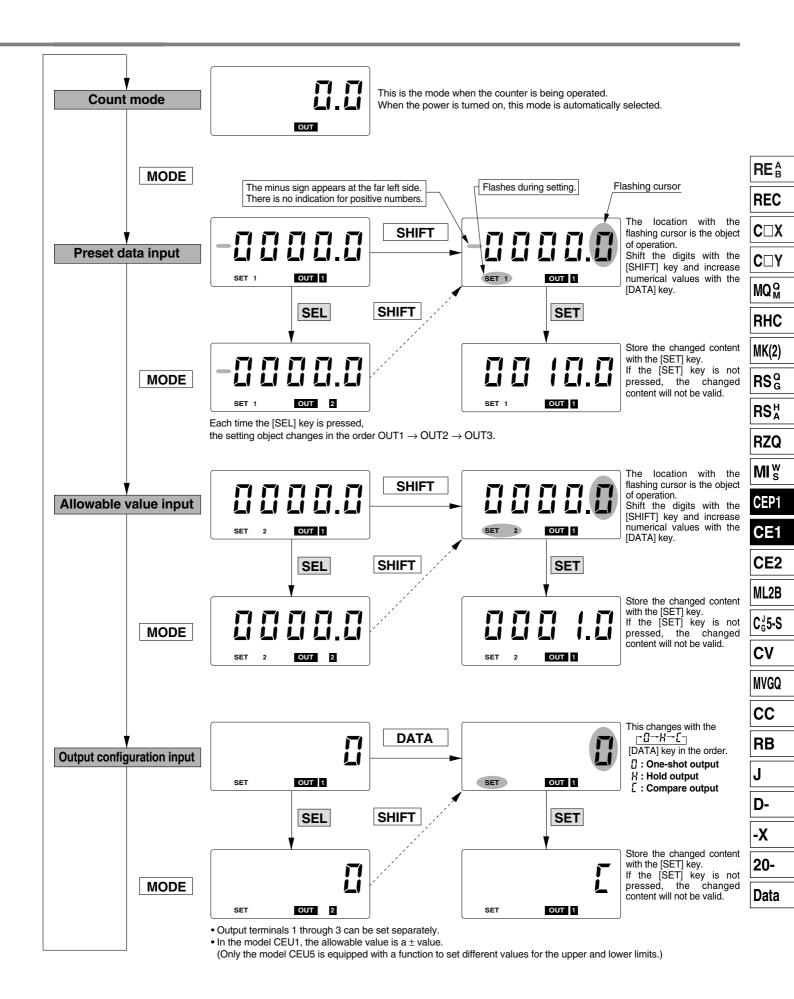
Key and Functions

Key	Functions
MODE	Switches between the count mode and the setting mode.
SHIFT	Switches digits for preset data input and allowable value input. Shifts the flashing cursor to the left each time it is pressed.
SEL	In the setting mode, this switches the output terminal number which is to be set. Switches in the order OUT1 \rightarrow OUT2 \rightarrow OUT3 each time it is pressed.
DATA	In the setting mode, this changes numerical values, or codes and symbols. Numerical values increase by 1 each time it is pressed. For positive and negative codes, a minus sign turns on or off.
SET	Registers the setting contents in the setting mode. Press this key to perform registration after making setting changes. The setting will not be registered if the screen is changed by pressing the [MODE] or [SEL] keys without pressing the [SET] key.

The counter mode changes in the order shown below each time the [MODE] key is pressed.



Counter CEU



Series CE

Glossary (Functions of CEU5)

BCD Output

This is a system which expresses one digit of a decimal number with a 4 digit binary number.

The count value is expressed by the ON/OFF state of each BCD output terminal. In the case of 6 digits, 24 terminals are required.

The relation between decimal numbers and BCD codes is shown in the table below.

Decimal no.	0	1	2	3	4	5	6	7	8	9
BCD	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001

Ex.) 1294.53 is expressed as follows. 0001 0010 1001 0100 0101 0011

RS-232C

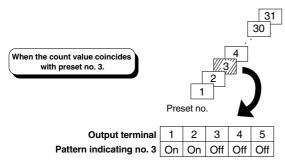
This is the interface standard for the serial transmission method, which is standard equipment on a personal computer.

Prescale Function

This function allows free setting of how many millimeters will indicate one pulse.

Binary Output

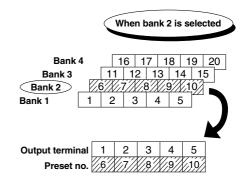
31 point preset output is possible without bank switching, by means of binary system output from a 5 point output terminal. Cylinder stop output is used as the readout release signal.



The coincident preset number is expressed as a 5 digit binary number.

Bank Function

5 points of preset output are possible simultaneously, however, a maximum of 20 types of work discrimination, etc. can be performed by using the 5 points of preset values as one of a maximum of four quadrats, and switching its use during operation.



For example, when bank 2 is selected, presets 6 through 10 are valid and when the count value coincides with the setting value of 6 through 10, the respective output terminals 1 through 5 are turned ON.

Bank Switching Correspondence

Input terminal Bank no.	BANK2	BANK1
1	OFF	OFF
2	OFF	ON
3	ON	OFF
4	ON	ON

Series CE

Glossary (Functions of CEU5)

Display Offset Function

Normally the count value returns to "0" after resetting, but with this function, the initial value can be set to any desired value.

Hold Function

When "hold" is input, the counter holds the current count value in memory. Next, when the count value is read into a PLC which uses serial or BCD output, etc., the count value that was held can be read in, even if there is a time lag.

Setting the Tolerances of Preset Values

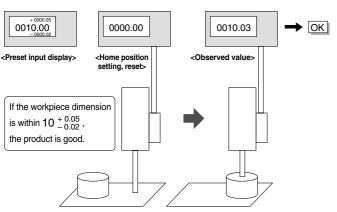
In the current model CEU1, the preset value tolerances could only be set as \pm , but now it has become possible to set an upper and lower limit of $+\bigcirc$ mm and $-\triangle$ mm.

By including preset tolerance setting, superior performance is exhibited in parts inspections, etc. In a workpiece to be measured, there are tolerances which assure a good product. For example, in the case of $10^{+0.05}_{-0.02}$, the CEU5 allows these tolerances to be input as they stand. If the workpiece is within tolerances the OK signal is sent.

On the other hand, in ordinary counters, no. 1 is set to 9.98 and no. 2 is set to 10.06, and if no. 1 is ON and no. 2 is OFF, an acceptance decision is made. 2 points of output are used in order to check whether or not the product is within dimension tolerances. In this example, one preset of the CEU5 performs the same function as two presets of an ordinary counter.

<Simple input as per drawing dimensions> Tolerances can be set with the preset value.

OK/NG signal is output by the counter. Labor savings can be realized in parts inspections.



Count Value Protection

In the past, the count value returned to "0" when the power supply was cut off, but this function holds the previous value even after a power failure. This function can be switched between active and inactive settings.

Cylinder Stop Output

When workpiece discrimination is performed using a preset counter, it has been common to estimate the amount of time from the cylinder's start of operation until it touches the workpiece and stops, using a timer to read the output after a fixed amount of time. Since cylinder stop output is now output when there is no cylinder movement for a fixed amount of time, timing of preset output and external output, etc. is simplified.

RE_B

REC

C□X

C□Y

MQ M

RHC

MK(2)

RS^Q_G

RS^H

RZQ

MI S CEP1

CE1

CE2

ML2B

CV

MVGQ

CC

RB

D-

-**X**

20-

