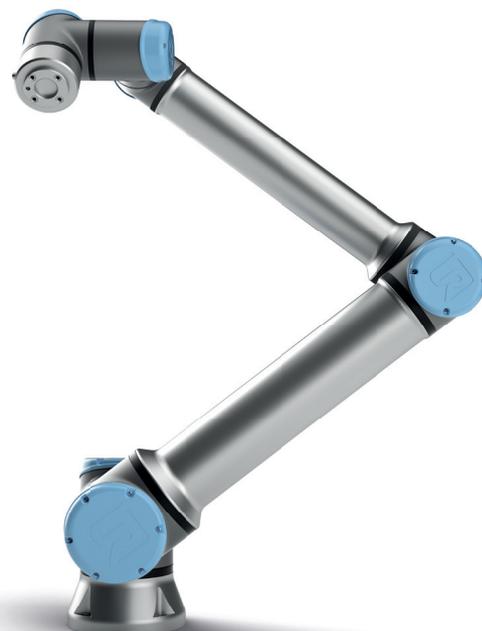


# UR10e technical details



## Performance

|                           |  |            |         |
|---------------------------|--|------------|---------|
| Power consumption         | Approx. 350 W using a typical program  |            |         |
| Collaboration operation   | 17 advanced adjustable safety functions incl. elbow monitoring.<br>Remote Control according to ISO 10218 |            |         |
| Certifications            | EN ISO 13849-1, Cat.3, PL d, and EN ISO 10218-1  |            |         |
| F/T Sensor - Force, x-y-z | F/T Sensor - Torque, x-y-z   |            |         |
| Range                     | 100 N  | Range      | 10 Nm   |
| Resolution                | 2.0 N  | Resolution | 0.02 Nm |
| Accuracy                  | 5.5 N  | Accuracy   | 0.60 Nm |
| Ambient temperature range | 0-50°C   |            |         |
| Humidity                  | 90% RH (non-condensing)  |            |         |

## Specification

|                    |   |  |  |
|--------------------|---|--|--|
| Payload            | 10 kg / 22 lbs  |  |  |
| Reach              | 1300 mm / 51.2 in   |  |  |
| Degrees of freedom | 6 rotating joints DOF   |  |  |
| Programming        | Polyscope graphical user interface on 12 inch touchscreen with mounting |  |  |

## Movement

|                         |   |               |  |
|-------------------------|---|---------------|--|
| Pose Repeatability      | +/- 0.05 mm, with payload, per ISO 9283 |               |  |
| Axis movement robot arm | Working range                           | Maximum speed |  |
| Base                    | ± 360°                                  | ±120°/Sec.    |  |
| Shoulder                | ± 360°                                  | ±120°/Sec.    |  |
| Elbow                   | ± 360°                                  | ±180°/Sec.    |  |
| Wrist 1                 | ± 360°                                  | ±180°/Sec.    |  |
| Wrist 2                 | ± 360°                                  | ±180°/Sec.    |  |
| Wrist 3                 | ± 360°                                  | ±180°/Sec.    |  |
| Typical TCP speed       | 1 m/Sec./<br>39.4 in/Sec.               |               |  |

## Features

|                          |  |   |  |
|--------------------------|--|---|--|
| IP classification        | IP54   |   |  |
| ISO Class Cleanroom      | 5  |   |  |
| Noise                    | Less than 65 dB(A)                               |   |  |
| Robot mounting           | Any Orientation                                  |   |  |
| I/O Ports                | Digital in                                       | 2 |  |
|                          | Digital out                                      | 2 |  |
|                          | Analog in  | 2 |  |
|                          | Analog out                                       | 0 |  |
|                          | UART interface (9.6k-5Mbps)                      |   |  |
| I/O power supply in tool | 12V/24V 600mA continuous, 2A for shorter periods |   |  |

## Physical

|                                    |                           |  |  |
|------------------------------------|---------------------------|--|--|
| Footprint                          | Ø 190 mm                  |  |  |
| Materials                          | Aluminium, Plastic, Steel |  |  |
| Tool (end-effector) connector type | M8   M8 8-pin             |  |  |
| Cable length robot arm             | 6 m / 236 in              |  |  |
| Weight including cable             | 33.5 kg / 73.9 lbs        |  |  |

## Control box

### Performance

|                           |  |    |  |
|---------------------------|--|----|--|
| IP classification         | IP44   |    |  |
| ISO Class Cleanroom       | 6  |    |  |
| Ambient temperature range | 0-50°C   |    |  |
| I/O Ports                 | Digital in   | 16 |  |
|                           | Digital out  | 16 |  |
|                           | Analog in  | 2  |  |
|                           | Analog out   | 2  |  |
|                           | 500 Hz control, 4 separated high speed quadrature digital inputs   |    |  |
| I/O power supply          | 24V 2A   |    |  |
| Communication             | Control frequency: 500 Hz<br>ModbusTCP: 500 Hz signal frequency<br>ProfiNet and EthernetIP: 500 Hz signal frequency<br>USB ports: 1 USB 2.0, 1 USB 3.0 |    |  |
| Power source              | 100-240 VAC, 47-440Hz  |    |  |
| Humidity                  | 90% RH (non-condensing)  |    |  |

### Physical

|                          |   |  |  |
|--------------------------|---|--|--|
| Control box size (WxHxD) | 475 mm x 423 mm x 268 mm<br>18.7 in x 16.7 in x 10.6 in |  |  |
| Weight                   | Max 13.6 kg / 30.0 lbs                                  |  |  |
| Materials                | Steel   |  |  |

## Teach pendant

### Features

|                    |                         |  |  |
|--------------------|-------------------------|--|--|
| IP classification  | IP54                    |  |  |
| Humidity           | 90% RH (non-condensing) |  |  |
| Display resolution | 1280 x 800 pixels       |  |  |

### Physical

|                                 |                   |  |  |
|---------------------------------|-------------------|--|--|
| Materials                       | Plastic           |  |  |
| Weight including 1m of TP cable | 1.6 kg / 3.5 lbs  |  |  |
| Cable length                    | 4.5 m / 177.17 in |  |  |



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